

AI Researches on Computer Graphics Vision LAB

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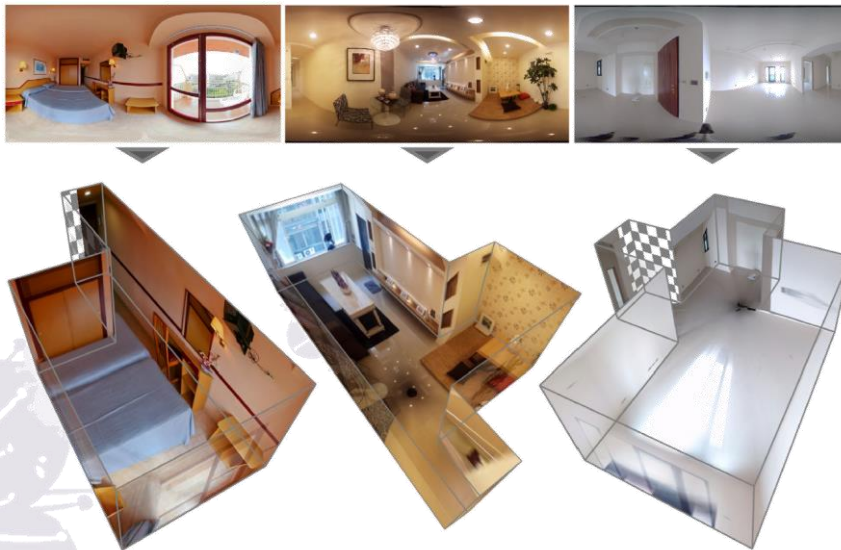
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Topic #1:

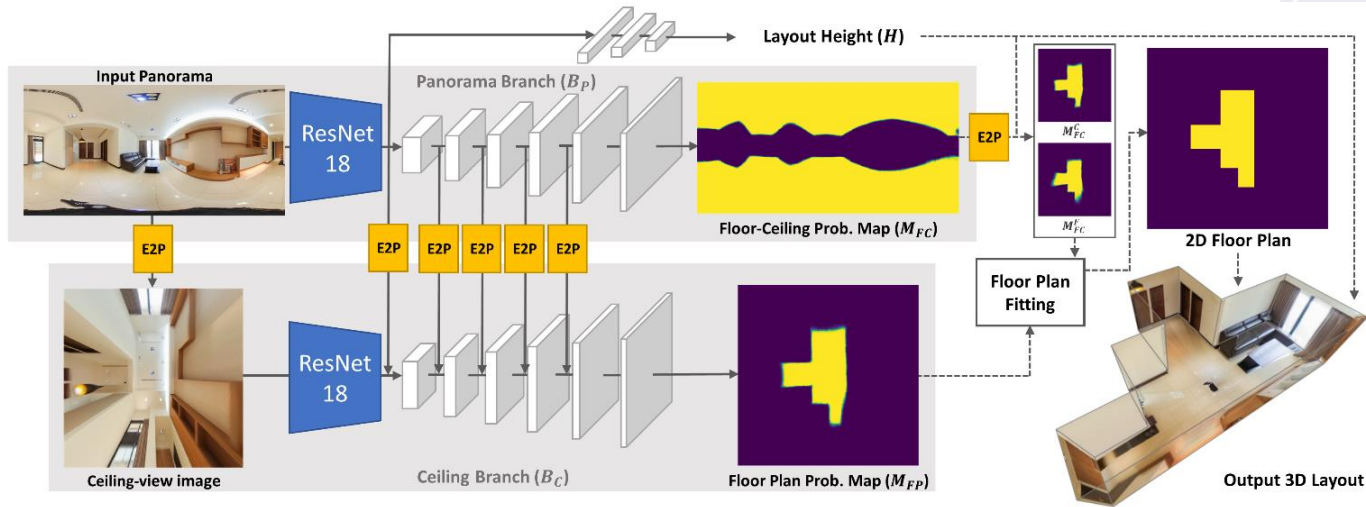
3D Room Layout Estimation

- A deep learning framework to predict Manhattan-world 3D room layouts from a single RGB panorama



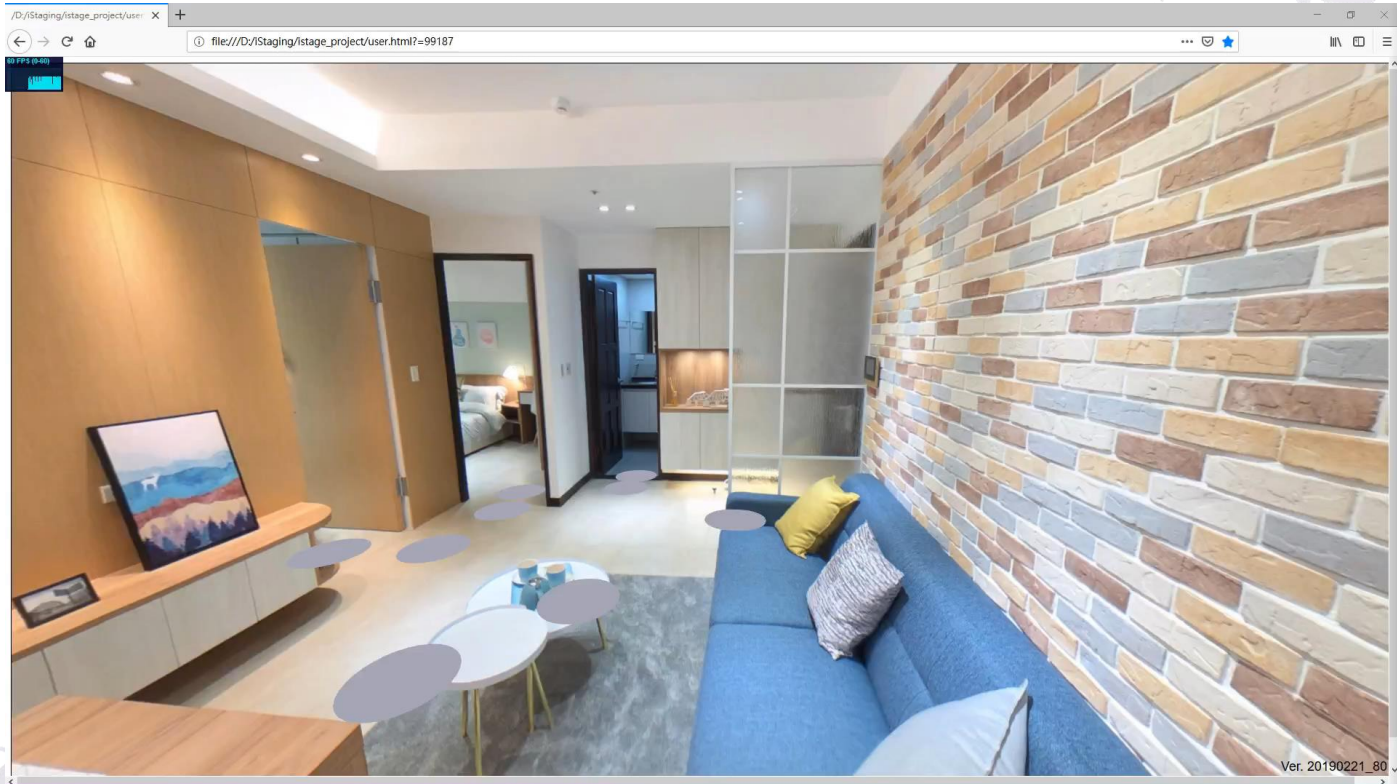
DuLa-Net: A Dual-Projection Network for Estimating Room Layouts from a Single RGB Panorama [CVPR 2019]

Shang-Ta Yang, Fu-En Wang, Chi-Han Peng, Peter Wonka, Min Sun, **Hung-Kuo Chu***

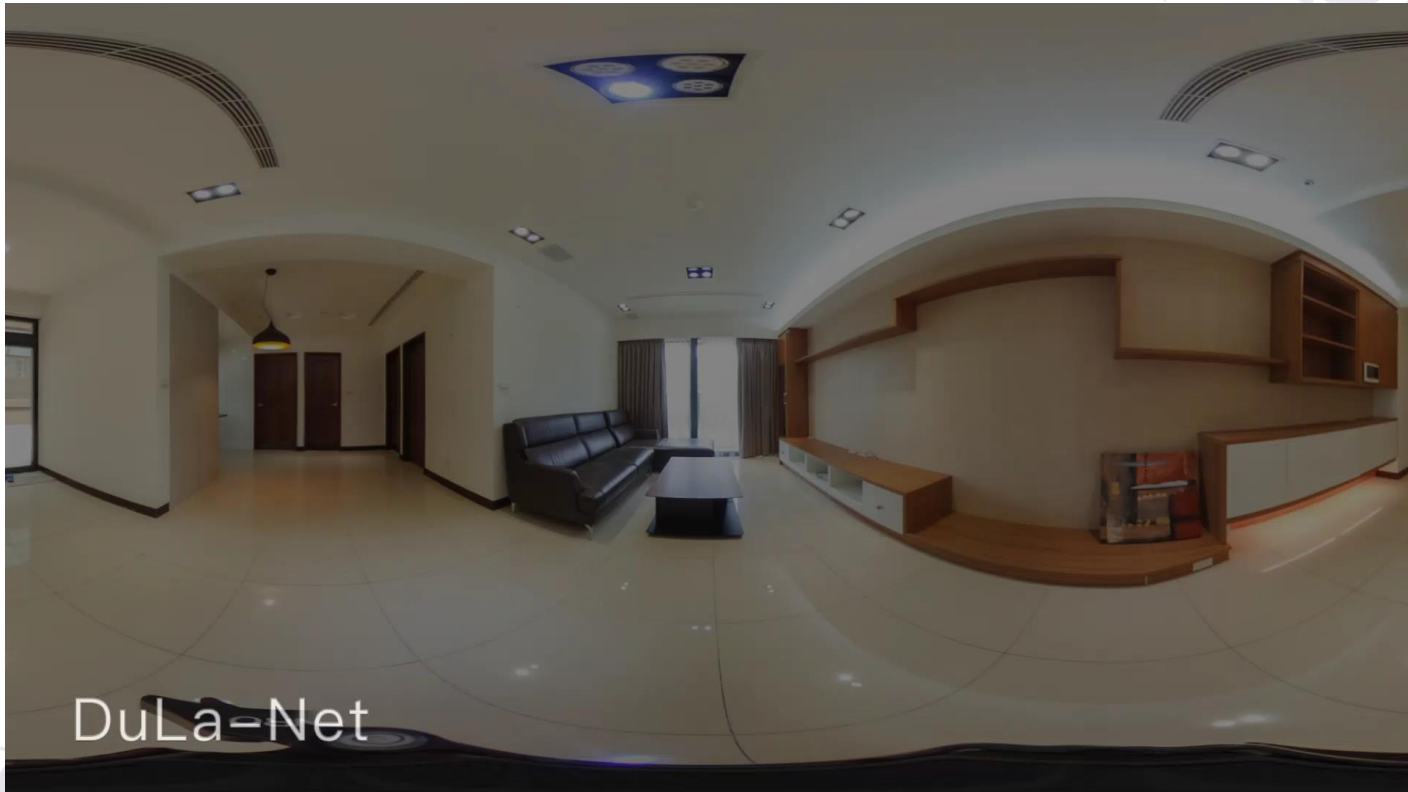


Method	Average	
	2D IoU (%)	3D IoU (%)
LayoutNet [33]	65.84	62.77
亮點：世界第一成效 15% improvement!!	75.2	72.02
	75.75	72.18
ours (w/o fusion)	78.52	74.8
ours (full)	80.53	77.2

Application : 360 Navigation



Application : VR Estate Tour

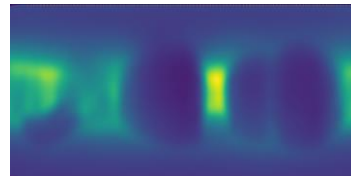
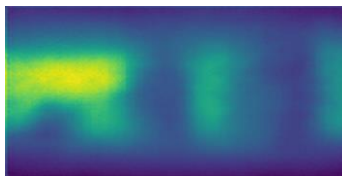
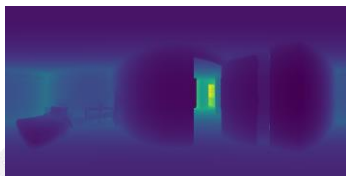
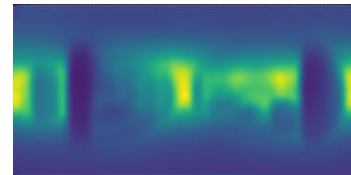
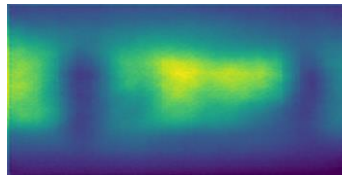
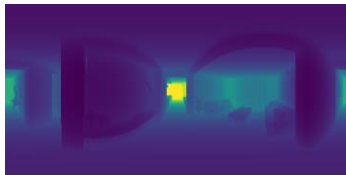
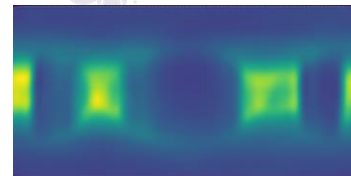
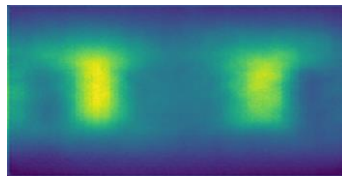
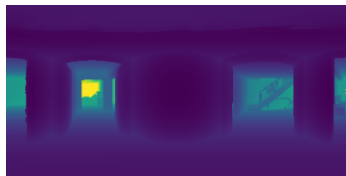


Cross-Viewpoint Consistency

- The model (perspective-domain) prediction on sampled views in a 360° image should **be consistent in the overlapping region.**



Depth Prediction



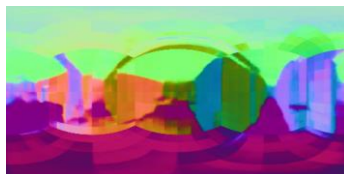
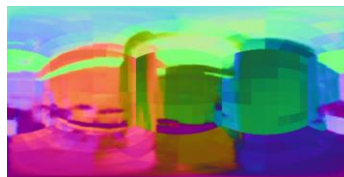
Input

Ground-truth

State-of-the-art

Our result

Surface Normal Estimation



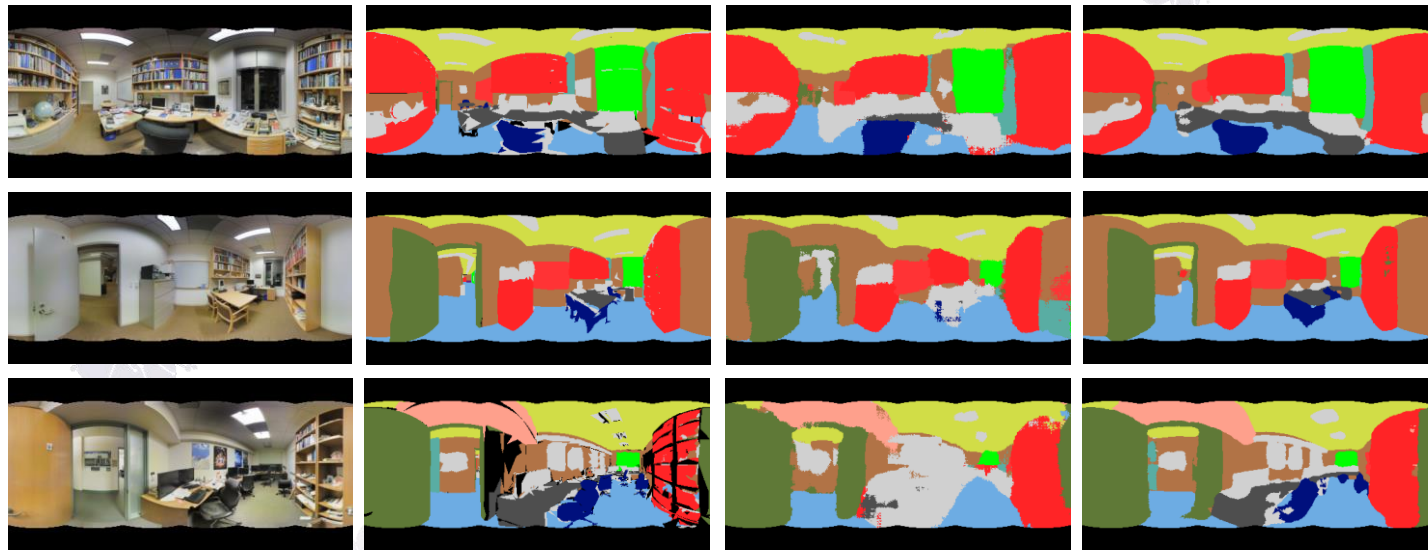
Input

Ground-truth

State-of-the-art

Our result

Semantic Segmentation

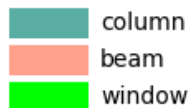
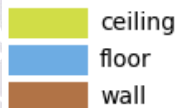


Input

Ground-truth

State-of-the-art

Our result



Topic #3:

Instance-aware Colorization

- We introduce a instance-aware colorization method to improve the quality of image colorization results.



Grayscale



State-of-the-art

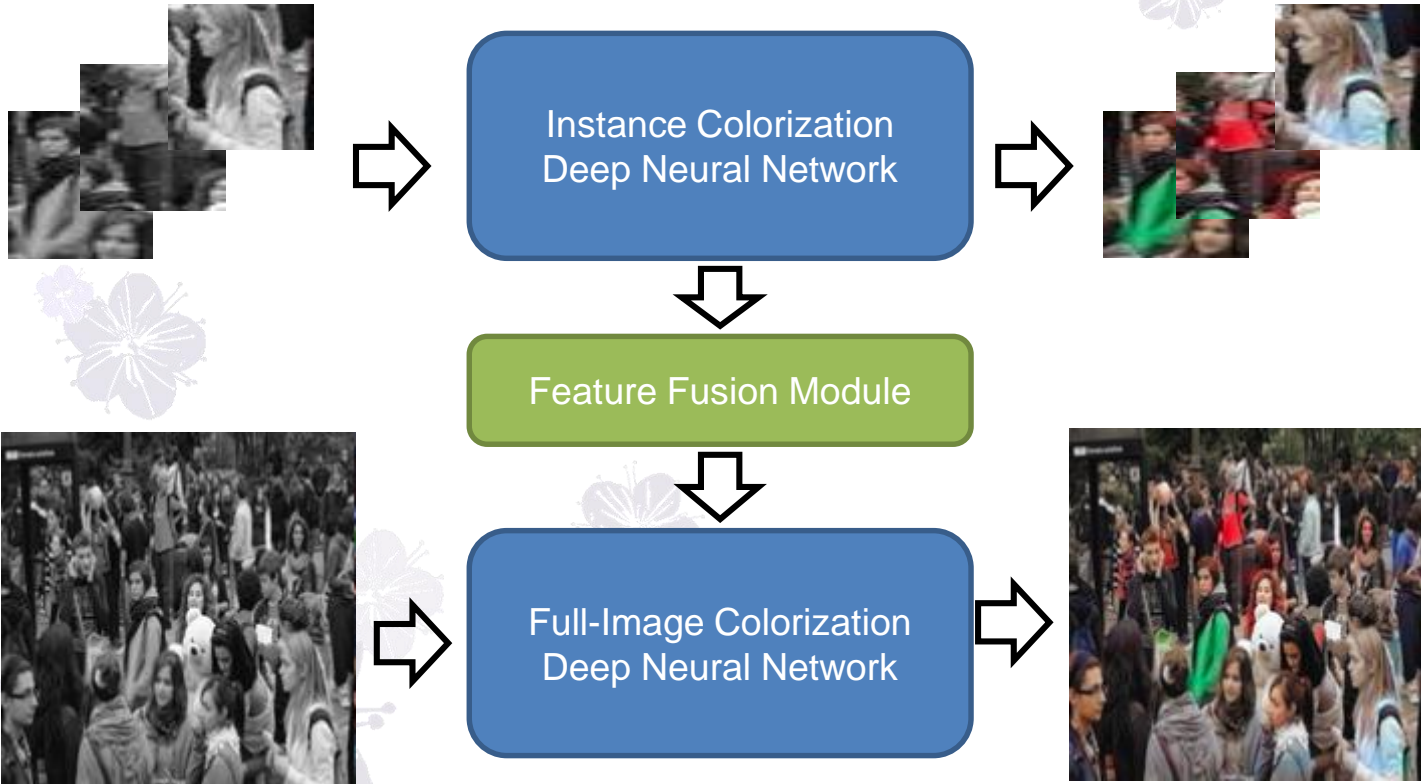


Our result



Ground-truth

Architecture



Results



Grayscale

State-of-the-art

Our result

Ground-truth